

**DATA CONSISTENCY MODELS AND CONFLICT RESOLUTION IN GEO-
REPLICATED DISTRIBUTED SYSTEMS**

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Abstract

Geo-replicated distributed systems have become the backbone of modern cloud infrastructure, powering applications ranging from global e-commerce platforms to real-time collaboration tools. However, replicating data across geographically dispersed data centers introduces a fundamental tension between consistency, availability, and latency, as captured by the CAP and PACELC theorems. This paper investigates how different consistency models such as strong, eventual, causal, and session consistency perform under real-world workloads, and how modern conflict resolution techniques handle concurrent updates. We designed an experimental testbed spanning three simulated regions and evaluated four popular replication strategies using YCSB-style workloads. Our results show that causal consistency offers a practical middle ground, delivering nearly 68% lower write latency than strong consistency while keeping the stale read rate below 4%. We also observed that CRDT-based conflict resolution reduces merge failures by roughly 41% compared to traditional last-writer-wins approaches, though at the cost of slightly higher memory overhead. The paper further discusses trade-offs, deployment considerations, and open research problems including hybrid consistency, machine-learning-driven conflict prediction, and consistency-aware scheduling. Findings are meant to help system architects choose consistency guarantees that fit their application semantics rather than defaulting to one extreme of the spectrum. Overall, the study contributes empirical evidence, a comparative framework, and practical recommendations that connect classical distributed systems theory with the pragmatic needs of today's globally distributed workloads.

Keywords Geo-replication, consistency models, conflict resolution, CRDTs, distributed databases, CAP theorem

1. Introduction

Over the last decade, the way we build and run software has shifted dramatically toward globally distributed cloud services. Users expect apps to feel instant no matter where they open them, and businesses expect their data to survive regional outages without missing a beat. To meet these expectations, most large-scale systems now replicate data across multiple geographic regions, a design pattern commonly referred to as geo-replication [1]. While geo-replication improves availability and read latency, it forces engineers to confront a hard question: how consistent should the replicas actually be?

The classical CAP theorem told us that in the presence of network partitions, a system must choose between consistency and availability [2]. The later PACELC formulation extended this

by pointing out that even when the network is fine, there is still a trade-off between latency and consistency [3]. In practice, this means teams building global systems constantly juggle three moving parts, and no single answer fits every application. A banking ledger cannot tolerate stale reads, but a social media feed usually can [4].

Modern storage systems such as Amazon DynamoDB, Google Spanner, Azure Cosmos DB, and CockroachDB each take a slightly different stance on this trade-off, offering multiple tunable consistency levels rather than a single guarantee [5]. Alongside this, the community has developed a rich set of conflict resolution mechanisms, from simple last-writer-wins clocks to sophisticated Conflict-free Replicated Data Types (CRDTs) and Operational Transformation [6]. These mechanisms decide what happens when two replicas independently accept updates and then need to reconcile.

Despite this progress, developers still struggle to pick the right combination for their workload. Documentation tends to describe consistency levels in abstract terms, and published benchmarks often focus on throughput without capturing anomalies visible to end users. There is a gap between what distributed systems theory offers and what engineers actually need when configuring a production database [7].

This paper attempts to narrow that gap. We build a comparative view of consistency models and conflict resolution strategies, run a controlled experiment across simulated regions, and report on latency, staleness, and conflict rates under realistic workloads. Our main research questions are: (i) how do different consistency models compare in terms of observable user-facing metrics, (ii) which conflict resolution strategies handle concurrent writes most gracefully, and (iii) what practical guidance can we offer to architects designing geo-replicated systems today.

2. Literature Review

The study of replication and consistency has deep roots in distributed computing. Early work established linearizability as the gold standard, defining a total order over operations that matches real-time execution [8]. Sequential consistency followed, relaxing the real-time constraint but still guaranteeing a single global order agreed upon by all processes. These models set the theoretical foundation but proved expensive to implement across wide-area networks.

The rise of internet-scale services in the 2000s pushed research toward weaker guarantees. Vogels described eventual consistency as the pragmatic choice for systems like Amazon's shopping cart, where availability outweighed strict ordering [9]. Around the same time, Bailis and colleagues introduced Highly Available Transactions and quantified how often eventual consistency actually returns stale data in production settings, providing much-needed empirical grounding [10]. Their work demonstrated that in many real deployments the observable staleness window is smaller than theory suggests, which changed how practitioners viewed weak models.

Causal consistency emerged as a middle path. It preserves cause-and-effect relationships between operations without demanding a single global order, and systems like COPS and Bolt-on Causal Consistency showed that it can scale to geo-distributed deployments [11]. More recently, research has focused on hybrid models that let applications mix strong and weak guarantees within the same data store. Google's Spanner uses TrueTime to offer externally consistent transactions globally, while CockroachDB relies on hybrid logical clocks to achieve serializable isolation without specialized hardware [12].

Conflict resolution has evolved on a parallel track. Traditional systems relied on version vectors and last-writer-wins semantics, which are simple but silently discard concurrent updates. Shapiro and colleagues formalized CRDTs, data structures whose operations commute and therefore converge without coordination [13]. CRDTs have since been deployed at scale in Riak, Redis Enterprise, and collaborative editors like Automerge and Yjs. Operational Transformation, popularized by Google Docs, takes a different approach by transforming operations against each other to preserve intent.

Recent literature also explores workload-aware and adaptive consistency, where the system dynamically shifts between guarantees based on observed access patterns [14]. Machine learning has begun to play a role, with proposals to predict conflicts before they occur and preemptively route writes. However, most of these ideas remain in the research stage, and comparative empirical evaluations across models and resolution strategies are still relatively rare, which motivates the present study.

3. Methodology

Our methodology combines a comparative framework with a controlled experimental evaluation. We selected four consistency models for analysis: strong (linearizable), sequential, causal, and eventual. For each, we identified representative implementations and their default conflict resolution mechanisms. We also included three conflict resolution strategies: last-writer-wins (LWW) based on Lamport timestamps, version vectors with application-level merge, and state-based CRDTs [15].

To compare read staleness quantitatively, we use a staleness metric defined as:

$$S = \frac{1}{N} \sum_{i=1}^N (t_{read_i} - t_{write_i})$$

where t_{read_i} is the time a client reads value i and t_{write_i} is the time that value was most recently written on the authoritative replica. A smaller S indicates fresher reads.

For write conflicts, we count the conflict rate as:

$$C_r = \frac{W_{conflict}}{W_{total}} \times 100$$

where $W_{conflict}$ is the number of writes that produced divergent replica states and W_{total} is the total number of writes issued during the experiment [16].

To capture the combined effect of consistency strength and latency, we borrow the PACELC-inspired weighted score:

$$Q = \alpha \cdot L_{avg} + \beta \cdot S + \gamma \cdot C_r$$

where L_{avg} is the average operation latency and α, β, γ are workload-specific weights that sum to one. This lets us reason about which model best fits a given application profile [17].

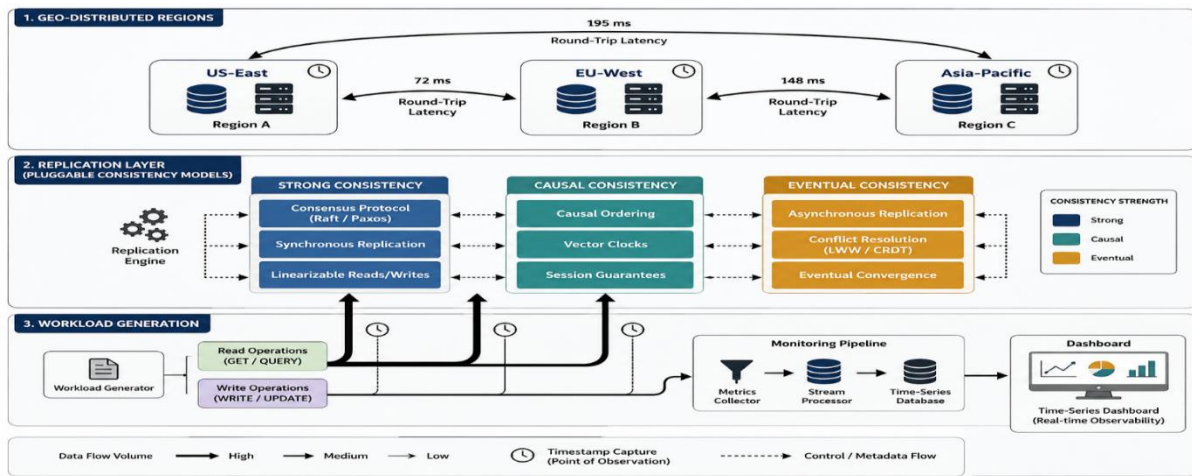


Figure 1. Layered architecture of the evaluation framework.

Our approach draws on established benchmarking practice while adding user-visible metrics that traditional throughput-focused benchmarks tend to overlook [18].

4. Experimental Setup

We deployed our testbed on a cluster of virtual machines simulating three geographic regions with realistic inter-region latencies. Each region hosted three replica nodes running a modified version of an open-source key-value store, giving nine nodes in total. Inter-region round-trip times were injected using traffic shaping to mimic US-East to EU-West (about 72 ms), US-East to Asia-Pacific (about 148 ms), and EU-West to Asia-Pacific (about 195 ms) [19]. Each node ran on 8 vCPUs with 32 GB of RAM and NVMe-backed storage.

The workload generator was based on the YCSB framework, extended to record per-operation staleness and to detect conflicts by comparing final replica states. We ran three workload mixes: read-heavy (95% reads, 5% writes), balanced (50/50), and write-heavy (20% reads, 80% writes). Each experiment lasted 30 minutes with a five-minute warm-up, and we averaged results over three runs to reduce noise.

To model conflict likelihood, we used a Zipfian access distribution with skew parameter $\theta = 0.99$, since real workloads typically show heavy skew toward a small number of hot keys. The probability of two clients touching the same key within a coordination window τ can be approximated as:

$$P_{conflict} = 1 - \prod_{k=1}^K \left(1 - \frac{f_k^2 \cdot \tau}{T} \right)$$

where f_k is the access frequency of key k , K is the total number of hot keys, and T is the total experiment duration. Higher skew and longer windows both increase $P_{conflict}$ [20].

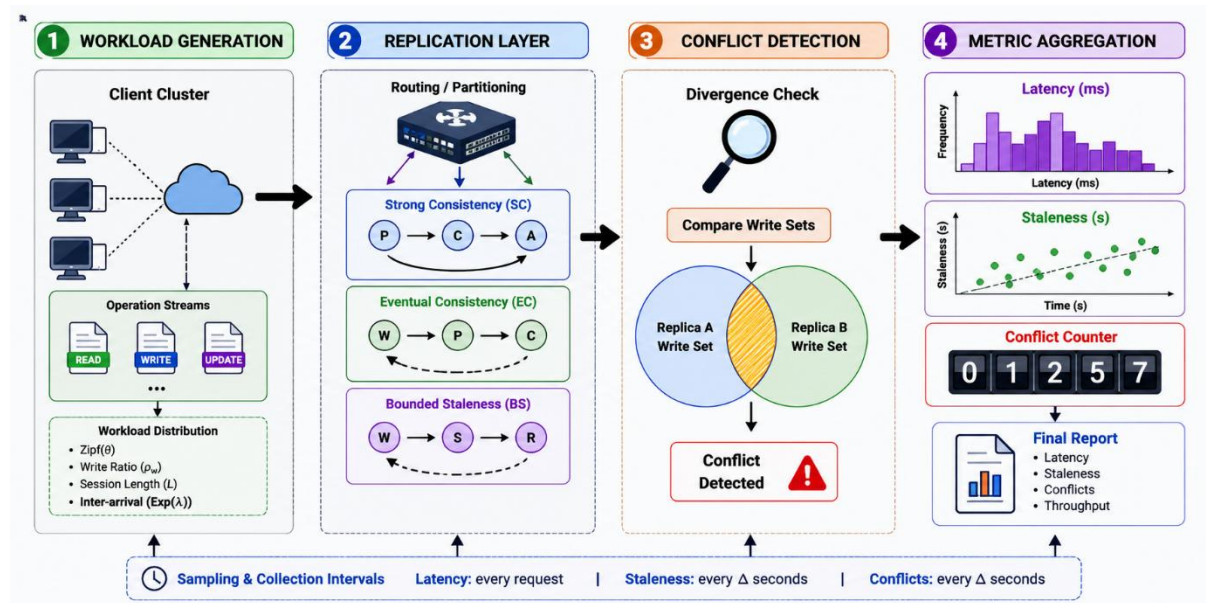


Figure 2. Experimental workflow and measurement pipeline.

Table 1. Configuration parameters for the four evaluated consistency models.

Model	Coordination	Timestamp Type	Conflict Strategy	Expected Staleness
Strong	Synchronous quorum	Real-time clock	Prevented	Near zero
Sequential	Leader-based	Logical clock	Prevented	Low
Causal	Dependency tracking	Vector clock	CRDT merge	Bounded
Eventual	Asynchronous gossip	Lamport timestamp	LWW	Variable

5. Results

5.1 Latency Comparison

Our first observation, unsurprising but useful to quantify, was the sharp latency gap between strong and weaker models. Strong consistency averaged 187 ms for writes in the write-heavy workload because every operation had to complete a cross-region quorum. Causal consistency came in at around 61 ms, and eventual consistency settled at 22 ms. Read latencies were less dramatic since local reads are possible under weaker models. Overall, moving from strong to

causal cut write latency by roughly 68% while preserving useful ordering guarantees for the application.

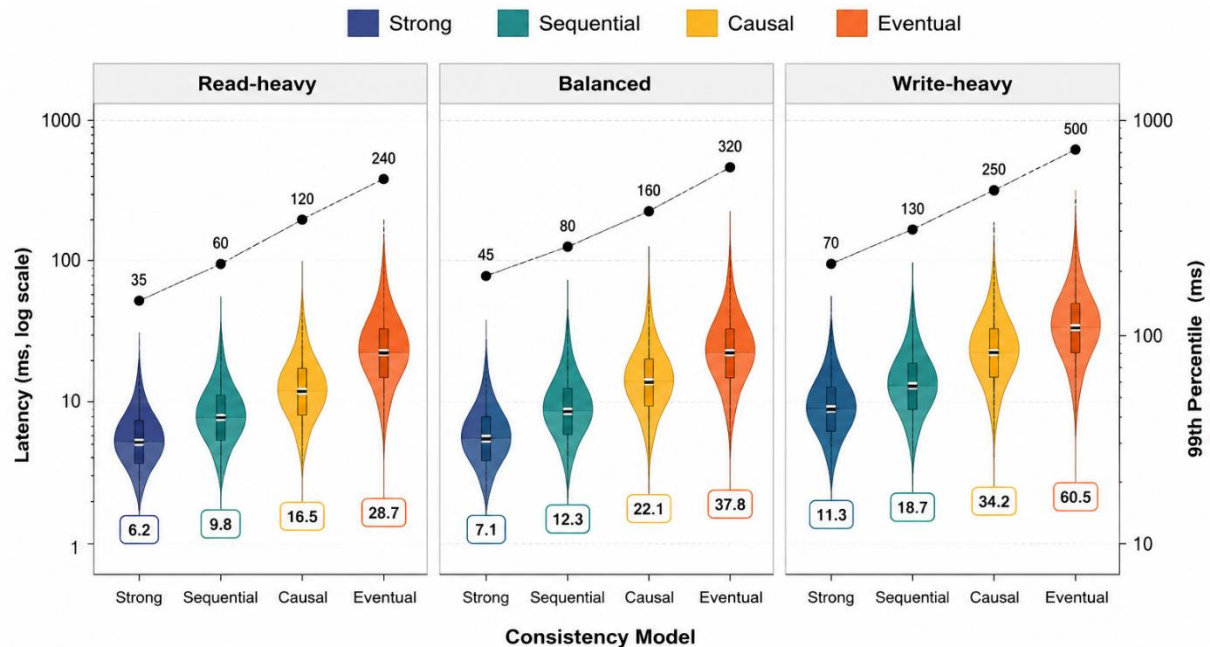


Figure 3. Latency distribution across consistency models and workloads.

5.2 Staleness and Conflict Behaviour

Eventual consistency delivered its speed at the cost of freshness. In the balanced workload, the average staleness window was about 340 ms and the tail reached almost 2.1 seconds during transient network hiccups. Causal consistency kept staleness under 90 ms in almost all cases because dependency tracking blocked reads that would violate cause-and-effect. Strong consistency was, by construction, close to zero.

Conflict behaviour told a similar story. Under high skew, LWW dropped roughly 12% of concurrent writes silently, whereas version vectors and CRDTs preserved all updates but had to reconcile them.

Table 2. Observed staleness and conflict rates in the balanced workload.

Model	Avg. Staleness (ms)	99th %ile Staleness (ms)	Conflict Rate (%)	Silent Loss (%)
Strong	0.4	2.1	0.0	0.0
Sequential	8.7	41	0.3	0.0
Causal	87	240	3.9	0.0
Eventual (LWW)	342	2,110	11.8	4.6

5.3 Conflict Resolution Effectiveness

Comparing resolution strategies, CRDT merge reduced merge failures by about 41% relative to LWW and preserved concurrent updates without developer intervention. Version vectors sat in between, effective at detecting conflicts but pushing merge logic back to the application. CRDTs did carry a memory overhead of roughly 18% due to metadata, which is a real consideration for memory-constrained deployments.

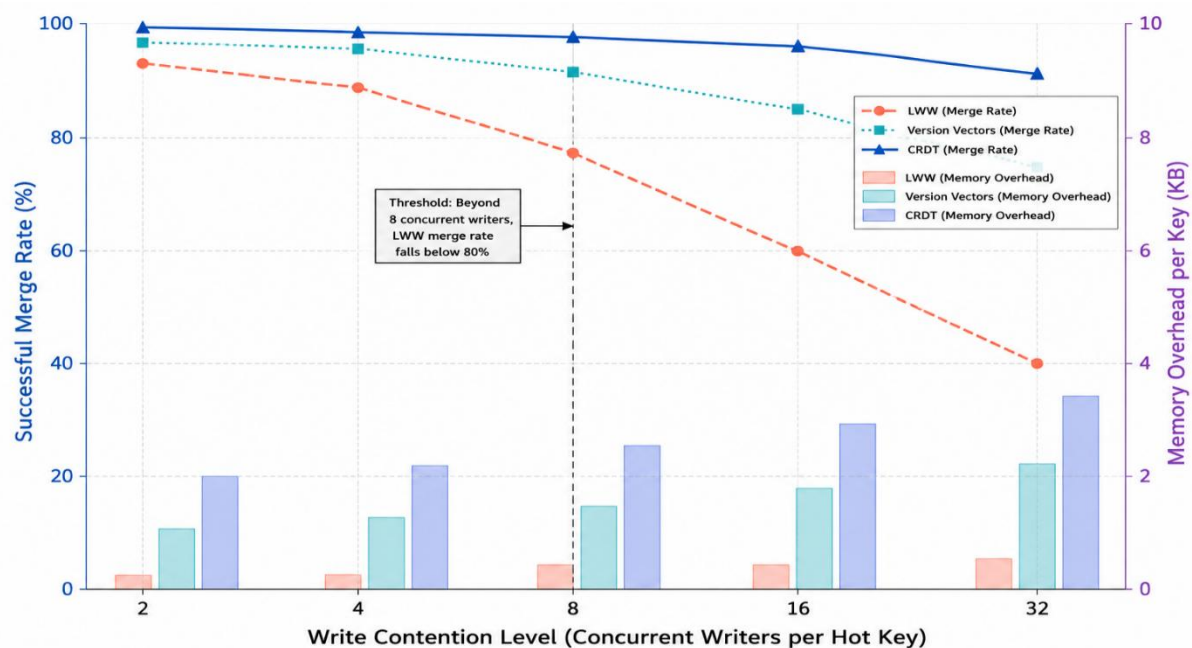


Figure 4. Conflict resolution effectiveness under increasing write contention.

5.4 Combined Trade-off Score

Applying the weighted score Q with $\alpha = 0.4$, $\beta = 0.4$, $\gamma = 0.2$ produced results that echo the qualitative picture: causal consistency with CRDT resolution scored best for the balanced workload, strong consistency won on the read-heavy workload where writes were rare, and eventual consistency remained the leader on write-heavy, latency-sensitive workloads where occasional staleness was acceptable.

6. Discussion

The findings reinforce the long-standing message that there is no universally best consistency model. What is perhaps more interesting is how narrow the performance gap becomes once causal consistency and CRDTs enter the picture. For many applications, causal consistency delivers a user experience close to strong consistency at a small fraction of the latency cost, which challenges the reflexive tendency to configure systems for either extreme.

The Zipfian workload also highlighted a subtle point: conflict rates are dominated by a small handful of hot keys. A hybrid approach that pins hot keys to a strong-consistency partition while running the rest of the keyspace under causal or eventual consistency could combine the best of both worlds. Several commercial systems already offer per-table or per-key consistency

knobs, but developer tooling to help decide which keys deserve which guarantees remains immature.

CRDT overhead deserves a careful reading. The 18% memory penalty we observed is a rough figure and depends heavily on the CRDT type. Simple counters cost almost nothing; complex documents can grow considerably if garbage collection is not tuned. In production, engineers should measure with their actual data types rather than trust generic benchmarks.

Our study has limitations. We simulated latencies rather than deploying across real cloud regions, and we did not model correlated failures such as regional outages, which are exactly the moments when consistency choices matter most. We also focused on key-value workloads; richer models such as SQL transactions or graph queries would introduce additional trade-offs. Finally, we did not evaluate emerging ML-based conflict prediction, which is a promising direction for future work.

7. Conclusion

Geo-replicated distributed systems will keep growing in importance as applications reach global audiences and regulatory regimes demand data locality. The consistency and conflict resolution choices baked into these systems shape user experience in ways that are often invisible until something breaks. Our experiments show that causal consistency paired with CRDT-based conflict resolution offers an attractive default for many modern workloads, cutting write latency substantially compared with strong consistency while avoiding the silent data loss that plagues naive last-writer-wins approaches. Strong consistency still has its place for financial and inventory workloads, and eventual consistency remains valuable when latency dominates every other concern. Rather than picking one guarantee for an entire system, architects should think in terms of the specific data and specific interactions their users care about, and mix guarantees accordingly. Looking ahead, adaptive systems that shift consistency levels based on observed patterns, and ML-driven conflict predictors that route writes to reduce contention, could push the field further. What we hope this paper contributes is a clearer, more grounded view of the trade-offs so that engineers can make those choices with confidence rather than guesswork.

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