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# OSCILLATION CRITERIA OF A CLASS OF FRACTIONAL ORDER DAMPED DIFFERENCE EQUATIONS

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**Abstract:** Herein, we examine the oscillatory behavior of all solutions of a fractional order difference equations with damping term of the form

$$\Delta^{1+\alpha}u(t) + p(t)\Delta^{\alpha}u(t) + q(t)F[G(t)] = 0, \quad t \ge t_0 > 0,$$

where  $G(t) = \sum_{s=t_0}^{t-1+\alpha} (t-s-1)^{-\alpha} u(s)$  and  $\Delta^{\alpha}$  denotes the Riemann-Liouville difference operator of order  $0 < \alpha \le 1$ . We arrive at some new sufficient conditions for the oscillation of solutions of fractional order damped difference equations using generalized riccati type transformation technique under suitable conditions.

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**Key Words:** oscillation, fractional order difference equations, Riccati technique, damping term

## 1. Introduction

Riccati type transformations are useful in the investigation of oscillation of solutions of differential/difference equations. Recently, paper [5] dealt with oscillation criteria of fractional differential equations. Motivated basically by this paper, and the cited papers in the references, we aim at obtaining some new oscillation theorems for a class of damped fractional order difference equations

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of the form

$$\Delta^{1+\alpha}u(t) + p(t)\Delta^{\alpha}u(t) + q(t)F[G(t)] = 0, \quad t \ge t_0 > 0,$$
(1)

where  $G(t) = \sum_{s=t_0}^{t-1+\alpha} (t-s-1)^{-\alpha} u(s)$  and  $\Delta^{\alpha}$  is the Riemann-Liouville difference operator of order  $0 < \alpha \le 1$ . Following assumptions are considered in the discussion of the this paper:

- $(C_1)$   $p:[t_0,\infty)\to R$  is a continuous function with p(t)<0.
- $(C_2)$   $q:[t_0,\infty)\to R$  is a continuous function with  $q(t)\geq 0$ .
- (C<sub>3</sub>)  $f: R \to R$  is a continuous function with uf(u) > 0 and there exists a constant m > 0 such that  $\frac{f(u)}{u} \ge m$  for all  $u \ne 0$ .

The problem of determining the oscillation of solutions of various equations like ordinary differential equations, difference equations, dynamic equations on timescales and functional differential equations has been a very active area of research in the last few decades (see [6], [7]). Recent years have witnessed the study of qualitative properties, especially oscillation of solutions of fractional difference equations (see [1], [2], [4], [9]) and the references therein.

By using Riccati type transformations, we establish some new sufficient conditions for the oscillation of solutions of equation (1). Therefore it is hoped that this paper will contribute to the study of oscillation for fractional order difference equations with damping term.

## 2. Preliminaries and Basic Results

This section introduces basic definitions and some preliminary results of discrete fractional calculus, which will be used throughout this paper.

**Definition 1.** (see [8]) A solution u(t) of (1) is said to be oscillatory if it is neither eventually positive nor eventually negative; otherwise, it is nonoscillatory. Equation (1) is said to be oscillatory if all its solutions are oscillatory.

**Definition 2.** (see [1], [3], [7]) Let  $\nu > 0$ . The  $\nu$ -th fractional sum f is defined by

$$\Delta^{-\nu} f(t) = \frac{1}{\Gamma(\nu)} \sum_{s=0}^{t-\nu} (t - s - 1)^{\nu - 1} f(s),$$

where f is defined for  $s \equiv a \mod (1)$  and  $\Delta^{-\nu} f$  is defined for  $t \equiv (a + \nu) \mod (1)$  and  $t^{(\nu)} = \frac{\Gamma(t+1)}{\Gamma(t-\nu+1)}$  and  $\Delta^{-\nu} f : N_a \to N_{a+\nu}$ .

**Definition 3.** (see [2], [3], [7]) Let  $\mu > 0$  and  $m - 1 < \mu < m$  where m denotes a positive integer  $m = \lceil \mu \rceil$ . Set  $\nu = m - \mu$ . The  $\mu$ -th fractional difference is defined as

$$\Delta^{\mu} f(t) = \Delta^{m-\nu} f(t) = \Delta^m \Delta^{-\nu} f(t).$$

**Theorem 4.** (see [1], [2]) Let u(t) be a solution of (1) and  $G(t) = \sum_{s=t_0}^{t-1+\alpha} (t-s-1)^{-\alpha} u(s)$ , then  $\Delta G(t) = \Gamma(1-\alpha) \Delta^{\alpha} u(t)$ .

**Theorem 5.** (see [5]) Let  $\alpha \in (0,1)$ , and t > 0. If u is a solution of (1), then  $(\Delta^{1+\alpha}u)(t) = \Delta(\Delta^{\alpha}u)(t)$ .

*Proof.* From Definition (3), by considering  $\mu = 1 + \alpha$ ,  $m = \lceil 1 + \alpha \rceil = 1 + \lceil \alpha \rceil = 1$  and  $\nu = 1 - \mu = 1 - (1 + \alpha) = -\alpha$ , we have

$$\left(\Delta^{1+\alpha}u\right)(t) = \Delta\Delta^{-(-\alpha)}u(t) = \Delta\left[\Delta^{\alpha}u(t)\right].$$

#### 3. Main Results

This section establishes some sufficient conditions of oscillation criteria results and inequalities.

**Theorem 6.** Suppose that  $(C_1) - (C_3)$  hold. If

$$\lim_{t \to \infty} \sum_{s=t_0}^{t-1} \left[ mq(s) - \frac{p^2(s)}{4\Gamma(1-\alpha)} \right] = \infty, \tag{2}$$

then every solution of equation (1) is oscillatory.

*Proof.* Suppose that u(t) is a non oscillatory solution of (1). Without loss of generality, we may take u(t) is an eventually positive solution of (1). Then

u(t) > 0 and G(t) > 0 for  $t \ge t_1 > t_0$ . Let us define the sequence  $\omega(t)$  by Riccati transformation as follows:

$$\omega(t) = -\frac{\Delta^{\alpha} u(t)}{G(t)} \quad \text{for } t \ge t_1.$$
 (3)

Here,  $\omega(t)$  is well defined and satisfies the inequality for  $t \geq t_1$ . It follows that

$$\Delta\omega(t) = -\Delta\left[\frac{\Delta^{\alpha}u(t)}{G(t)}\right] = \frac{[\Delta^{\alpha}u(t)]\Delta G(t)}{G(t)G(t+1)} - \frac{\Delta[\Delta^{\alpha}u(t)]}{G(t+1)}.$$

Applying Theorem (4) and Theorem (5) to (1), we get

$$\Delta\omega(t) = \frac{\Gamma(1-\alpha)\left(\Delta^{\alpha}u(t)\right)^{2}}{G(t)G(t+1)} + p(t)\frac{\Delta^{\alpha}u(t)}{G(t+1)} + q(t)\frac{F[G(t)]}{G(t+1)}.$$

Since  $\Delta G(t)$  is a non increasing function, we have

$$\Delta\omega(t) > \frac{\Gamma(1-\alpha)\left(\Delta^{\alpha}u(t)\right)^{2}}{\left(G(t)\right)^{2}} + p(t)\frac{\Delta^{\alpha}u(t)}{G(t)} + q(t)\frac{F[G(t)]}{G(t)}.$$

From (3) and  $(C_3)$ , we get

$$\Delta\omega(t) > \Gamma(1-\alpha)\omega^2(t) - p(t)\omega(t) + mq(t). \tag{4}$$

Let us sum the above expression (4) from  $t_1$  to t-1 on both sides, we obtain

$$\begin{split} &\sum_{s=t_1}^{t-1} \Delta \omega(s) > \sum_{s=t_1}^{t-1} \left[ \Gamma(1-\alpha)\omega^2(s) - p(s)\omega(s) + mq(s) \right] \\ &= \Gamma(1-\alpha) \sum_{s=t_1}^{t-1} \left( \left[ \omega(s) - \frac{p(s)}{2\Gamma(1-\alpha)} \right]^2 + \left[ mq(s) - \frac{p^2(s)}{4\Gamma(1-\alpha)} \right] \right). \end{split}$$

In view of (2), there exists  $t_2 \geq t_1$  such that

$$\omega(t) > \Gamma(1-\alpha) \sum_{s=t_1}^{t-1} \left[ \omega(s) - \frac{p(s)}{2\Gamma(1-\alpha)} \right]^2 \quad \text{for} \quad t > t_2.$$

Now we take  $H_1(t) = \Gamma(1-\alpha) \sum_{s=t_1}^{t-1} \left[ \omega(s) - \frac{p(s)}{2\Gamma(1-\alpha)} \right]^2$ , then  $\omega(t) > H_1(t)$  for  $t \ge t_1$ . From  $H_1(t)$  applying the fact that p(t) < 0, we can

easily see that,

$$\Delta H_1(t) = \Gamma(1-\alpha)\Delta \left[ \sum_{s=t_1}^{t-1} \left[ \omega(s) - \frac{p(s)}{2\Gamma(1-\alpha)} \right]^2 \right]$$

$$> \Gamma(1-\alpha)H_1^2(t), \quad \text{for } t > t_1$$

$$\Gamma(1-\alpha) < \frac{\Delta H_1(t)}{H_1^2(t)}.$$

Now summing the above expression from  $t_2$  to t-1, we have

$$\sum_{s=t_2}^{t-1} \Gamma(1-\alpha) < \sum_{s=t_2}^{t-1} \frac{\Delta H_1(s)}{H_1^2(s)} < \sum_{s=t_2}^{t-1} \left[ \frac{H_1(s+1)}{H_1^2(s)} - \frac{H_1(s)}{H_1^2(s)} \right].$$

Since  $\Delta H_1(t)$  is a non decreasing sequence, we have

$$\sum_{s=t_2}^{t-1} \Gamma(1-\alpha) < \sum_{s=t_2}^{t-1} \left[ \frac{1}{H_1(s+1)} - \frac{1}{H_1(s)} \right] < \frac{1}{H_1(t)} - \frac{1}{H_1(t_2)} < \frac{1}{H_1(t_2)}.$$

Letting  $t \to \infty$ ,  $\lim_{t \to \infty} \sum_{s=t_0}^{t-1} \Gamma(1-\alpha) < \frac{1}{H_1(t_2)}$ . This leads to a contradiction, which completes the proof of the theorem.

**Theorem 7.** Assume that  $(C_1)$  to  $(C_3)$  holds; and a positive double sequence H(t,s) such that

$$H(t,t) = 0$$
 for  $t > t_0$ ;  $H(t,s) > 0$  for  $t > s > t_0$   
 $\Delta_s H(t,s) = H(t,s+1) - H(t,s) \le 0$  for  $t > s > t_0$ .

If

$$\lim_{t \to \infty} Sup \frac{1}{H(t, t_0)} \sum_{s=t_0}^{t-1} \left[ mq(s)H(t, s) - \frac{h_+^2(t, s)k}{4\Gamma(1 - \alpha)H(t, s)} \right] = \infty$$
 (5)

where  $h_+(t,s) = \Delta_s H(t,s) - p(s)H(t,s)$ , then every solution of equation (1) is oscillatory.

*Proof.* Suppose to the contrary that u(t) is a non-oscillatory solution of (1). Without loss of generality, we take u(t) is an eventually positive solution of (1). Proceeding as in Theorem - 6, we arrive at the equation (4). Now multiplying

by H(t,s) and taking summation from  $t_1$  to t-1, we get

$$-\sum_{s=t_{1}}^{t-1} mq(s)H(t,s) > -\sum_{s=t_{1}}^{t-1} H(t,s)\Delta\omega(s)$$

$$\sum_{s=t_{1}}^{t-1} \left[\Gamma(1-\alpha)\omega^{2}(s)H(t,s) - p(s)\omega(s)H(t,s)\right].$$
(6)

Summation by parts formula yields

$$-\sum_{s=t_1}^{t-1} H(t,s)\Delta\omega(s) = H(t,t_1)\omega(t_1) + \sum_{s=t_1}^{t-1} \omega(s+1)\Delta_s H(t,s).$$
 (7)

Using equation (7) in (6) yields

$$-\sum_{s=t_1}^{t-1} mq(s)H(t,s) > H(t,t_1)\omega(t_1) + \sum_{s=t_1}^{t-1} \omega(s+1)\Delta_s H(t,s) + \sum_{s=t_1}^{t-1} \left[\Gamma(1-\alpha)\omega^2(s)H(t,s) - p(s)\omega(s)H(t,s)\right].$$

Since  $\Delta\omega(t)>0$ , we see that  $\omega(t+1)>\omega(t)$  and we get

$$-\sum_{s=t_{1}}^{t-1} mq(s)H(t,s) > H(t,t_{1})\omega(t_{1}) +$$

$$\sum_{s=t_{1}}^{t-1} \left[ (\Delta_{s}H(t,s) - p(s)H(t,s)) \omega(s) + \Gamma(1-\alpha)\omega^{2}(s)H(t,s) \right]$$

$$-\sum_{s=t_{1}}^{t-1} mq(s)H(t,s) > H(t,t_{1})\omega(t_{1}) +$$

$$\sum_{s=t_{1}}^{t-1} \left[ \Gamma(1-\alpha)H(t,s)\omega^{2}(s) + h_{+}(t,s)\omega(s) \right],$$
(8)

where  $h_{+}(t,s) = \Delta_{s}H(t,s) - p(s)H(t,s)$ . Now

$$\begin{split} \sum_{s=t_1}^{t-1} \left[ \Gamma(1-\alpha) H(t,s) \omega^2(s) + h_+(t,s) \omega(s) \right] &= -\sum_{s=t_1}^{t-1} \frac{h_+^2(t,s)}{4\Gamma(1-\alpha) H(t,s)} \\ &+ \sum_{s=t_1}^{t-1} \left[ \sqrt{\Gamma(1-\alpha) H(t,s)} \omega(s) + \frac{h_+(t,s)}{2\sqrt{\Gamma(1-\alpha) H(t,s)}} \right]^2 \end{split}$$

$$\sum_{s=t_1}^{t-1} \left[ \Gamma(1-\alpha) H(t,s) \omega^2(s) + h_+(t,s) \omega(s) \right] > - \sum_{s=t_1}^{t-1} \frac{h_+^2(t,s)}{4 \Gamma(1-\alpha) H(t,s)}.$$

Using the above equation in (8), we get the following inequality

$$-\sum_{s=t_1}^{t-1} mq(s)H(t,s) > H(t,t_1)\omega(t_1) - \sum_{s=t_1}^{t-1} \frac{h_+^2(t,s)k}{4\Gamma(1-\alpha)H(t,s)}$$

$$-H(t,t_1)\omega(t_1) > \sum_{s=t_1}^{t-1} \left[ mq(s)H(t,s) - \frac{h_+^2(t,s)k}{4\Gamma(1-\alpha)H(t,s)} \right]$$

$$\sum_{s=t_1}^{t-1} \left[ mq(s)H(t,s) - \frac{h_+^2(t,s)k}{4\Gamma(1-\alpha)H(t,s)} \right] < H(t,t_0)\omega(t_1).$$
 (9)

Since  $\Delta_s H(t,s) \leq 0$  for  $t > s \geq t_0$  and  $0 < H(t,t_1) \leq H(t,t_0)$  for  $t > s \geq t_0$ . Also  $0 < H(t,s) \leq H(t,t_0)$  for  $t > s \geq t_0$ , then  $0 < \frac{H(t,s)}{H(t,t_0)} \leq 1$  for  $t > s \geq t_0$ . Hence

$$\begin{split} \frac{1}{H(t,t_0)} \sum_{s=t_0}^{t-1} \left[ mq(s)H(t,s) - \frac{h_+^2(t,s)k}{4\Gamma(1-\alpha)H(t,s)} \right] \leq \\ \frac{1}{H(t,t_0)} \sum_{s=t_0}^{t_1-1} \left[ mq(s)H(t,s) - \frac{h_+^2(t,s)k}{4\Gamma(1-\alpha)H(t,s)} \right] + \\ \frac{1}{H(t,t_0)} \sum_{s=t_1}^{t-1} \left[ mq(s)H(t,s) - \frac{h_+^2(t,s)k}{4\Gamma(1-\alpha)H(t,s)} \right]. \end{split}$$

Using (9) in the above inequality, we obtain

$$\frac{1}{H(t,t_0)} \sum_{s=t_0}^{t-1} \left[ mq(s)H(t,s) - \frac{h_+^2(t,s)k}{4\Gamma(1-\alpha)H(t,s)} \right] \le \frac{1}{H(t,t_0)} \sum_{s=t_0}^{t_1-1} \left[ mq(s)H(t,s) - \frac{h_+^2(t,s)k}{4\Gamma(1-\alpha)H(t,s)} \right] + \omega(t_1)$$

$$\frac{1}{H(t,t_0)} \sum_{s=t_0}^{t-1} \left[ mq(s)H(t,s) - \frac{h_+^2(t,s)k}{4\Gamma(1-\alpha)H(t,s)} \right] < \omega(t_1) + \sum_{s=t_0}^{t_1-1} mq(s)$$

Letting  $t \to \infty$ , we get

$$\lim_{t \to \infty} \operatorname{Sup} \frac{1}{H(t, t_0)} \sum_{s=t_0}^{t-1} \left[ mq(s)H(t, s) - \frac{h_+^2(t, s)k}{4\Gamma(1 - \alpha)H(t, s)} \right] < \omega(t_1) + \sum_{s=t_0}^{t_1-1} mq(s) < \infty,$$

which is a contradiction to (5). This completes the proof.

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