

## GOPPA CODES OVER CERTAIN SEMIGROUPS

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**Abstract:** A Goppa code is described in terms of a polynomial, known as Goppa polynomial, and in contrast to cyclic codes, where it is difficult to estimate the minimum Hamming distance  $d$  from the generator polynomial. Furthermore, a Goppa code has the property that  $d \geq \deg(h(X)) + 1$ , where  $h(X)$  is a Goppa polynomial. In this paper, we present a decoding principle for Goppa codes constructed by generalized polynomials, which is based on modified Berlekamp-Massey algorithm.

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## 1. Introduction

Let  $(S, *)$  be a commutative semigroup and  $(R, +, \cdot)$  a commutative associative ring. The set  $J$  of all finitely nonzero functions  $f$  from  $S$  into  $R$  is a ring with respect to binary operations addition and multiplication defined as  $(f + g)(s) = f(s) + g(s)$  and  $(fg)(s) = \sum_{t*u=s} f(t)g(u)$ , where the symbol  $\sum_{t*u=s}$  indicates that the sum is taken over all pairs  $(t, u)$  of elements of  $S$  such that  $t*u = s$  and if  $s$  is not expressible in the form  $t*u$  for any  $t, u \in S$ , then  $(fg)(s) = 0$ . The set  $J$  is known as *semigroup ring* of  $S$  over  $R$ . If  $S$  is a monoid, then  $J$  is called monoid ring. This ring  $J$  is represented as  $B[S]$ , where  $S$  is a multiplicative semigroup, and the elements of  $J$  are written either as  $\sum_{s \in S} f(s)s$  or as  $\sum_{i=1}^n f(s_i)s_i$ . The representation of  $J$  will be  $R[X; S]$  whenever  $S$  is an additive semigroup. As there is an isomorphism between additive semigroup  $S$  and multiplicative semigroup  $\{X^s : s \in S\}$ , it follows that a nonzero element  $f$  of  $R[X; S]$  is uniquely represented in the canonical form  $\sum_{i=1}^n f(s_i)X^{s_i} = \sum_{i=1}^n f_iX^{s_i}$ , where  $f_i \neq 0$  and  $s_i \neq s_j$  for all  $i \neq j$ . Degree is not generally defined in commutative semigroup rings but if the semigroup  $S$  is a totally ordered semigroup, we can define the degree of a generalized polynomial of the semigroup ring  $R[X; S]$ . If  $f = \sum_{i=1}^n f_iX^{s_i}$  is the canonical form of the nonzero element  $f \in R[X; S]$ , where  $s_1 < s_2 < \dots < s_n$ , then  $s_n$  is called the degree of  $f$  and we write  $\deg(f) = s_n$ .

## 2. Goppa Code

Let  $(B, N)$  be a finite local commutative ring with unity and  $\mathbb{K}$  the residue field  $\frac{B}{N} \cong GF(p^m)$ , where  $p$  is a prime,  $m$  a positive integer. The natural projection  $\pi : B[X; \frac{1}{3}\mathbb{Z}_0] \rightarrow \mathbb{K}[X; \frac{1}{3}\mathbb{Z}_0]$  is defined by  $\pi(a(X^{\frac{1}{3}})) = \bar{a}(X^{\frac{1}{3}})$ , i.e.,  $\pi(\sum_{i=0}^n a_iX^{\frac{1}{3}i}) = \sum_{i=0}^n \bar{a}_iX^{\frac{1}{3}i}$ , where  $\bar{a}_i = a_i + N$ . Let  $f(X^{\frac{1}{3}})$  be a monic pseudo polynomial of degree  $t$  in  $B[X; \frac{1}{3}\mathbb{Z}_0]$  such that  $\pi(f(X^{\frac{1}{3}}))$  is irreducible in  $\mathbb{K}[X; \frac{1}{3}\mathbb{Z}_0]$ . Since  $B[X; \mathbb{Z}_0] \subseteq B[X; \frac{1}{3}\mathbb{Z}_0]$  [1, Theorem 7.2], it follows that  $f(X^{\frac{1}{3}})$  is also irreducible in  $B[X; \frac{1}{3}\mathbb{Z}_0]$ , by [2, Theorem XIII.7]. If  $\mathfrak{R} = \frac{B[X; \frac{1}{3}\mathbb{Z}_0]}{(f(X^{\frac{1}{3}}))}$ , then  $\mathfrak{R}$  is a finite commutative local factor semigroup ring with unity and again by [1, Theorem 7.2] accommodate our notions to say that it is a Galois ring extension of  $B$  with extension degree  $t$ . Its residue field is  $\mathbb{K}_1 = \frac{\mathfrak{R}}{N_1} = GF(p^{3mt})$ , where  $N_1$  is the maximal ideal of  $\mathfrak{R}$ , and  $\mathbb{K}_1^*$  is the multiplicative group of  $\mathbb{K}_1$  whose order is  $p^{3mt} - 1$ .

Let  $\mathfrak{R}^*$  denote the multiplicative group of units of  $\mathfrak{R}$  and  $\mathfrak{R}^*$  being an Abelian

group can be expressed as a direct product of cyclic groups. Our focus is in the maximal cyclic subgroup of  $\mathfrak{R}^*$ , hereafter denoted by  $G_s$ , whose elements are the roots of  $X^s - 1$  for some positive integer  $s$ . There is only one maximal cyclic subgroup of  $\mathfrak{R}^*$  having order  $s = p^{3mt} - 1$ . Let  $\beta = \alpha^{\frac{1}{3}}$  be a primitive element of the cyclic group  $G_s$ , where  $s = p^{3mt} - 1$ . Let  $h(X^{\frac{1}{3}}) = h_0 + h_1X^{\frac{1}{3}} + h_2(X^{\frac{1}{3}})^2 + \cdots + h_{3r}(X^{\frac{1}{3}})^{3r}$  be a polynomial with coefficients in  $\mathfrak{R}$  and  $h_{3r} \neq 0$ . Let  $T = \{\alpha_1, \alpha_2, \dots, \alpha_n\}$  be a subset of distinct elements of  $G_s$  such that  $h(\alpha_i)$  are units from  $\mathfrak{R}$  for  $i = 1, 2, \dots, n$ .

**Definition 1.** [3, Definition 4] A shortened Goppa code  $C(T, h)$  of length  $n \leq s$  is a code over  $B$  that has parity-check matrix

$$H = \begin{bmatrix} h(\alpha_1)^{-1} & \cdots & h(\alpha_n)^{-1} \\ \alpha_1 h(\alpha_1)^{-1} & \cdots & \alpha_n h(\alpha_n)^{-1} \\ \vdots & \ddots & \vdots \\ \alpha_1^{3r-1} h(\alpha_1)^{-1} & \cdots & \alpha_n^{3r-1} h(\alpha_n)^{-1} \end{bmatrix}, \quad (1)$$

where  $r$  is a positive integer,  $\eta = (\alpha_1, \alpha_2, \dots, \alpha_n)$  is the locator vector, consisting of distinct elements of  $G_s$  and  $\omega = (h(\alpha_1)^{-1}, \dots, h(\alpha_n)^{-1})$  is a vector consisting on elements of  $G_s$ .

**Theorem 1.** (see Theorem 7, [4]) *The Goppa code  $C(T, h)$  has minimum Hamming distance  $d \geq 3r + 1$ .*

### 3. Decoding Procedure

The decoding algorithm is based on the modified Berlekamp-Massey algorithm [5] which corrects all errors up to the Hamming weight  $t \leq \frac{3r}{2}$ , i.e., whose minimum Hamming distance is  $3r + 1$ . The decoding procedure for these codes consists of four major steps: calculation of the syndromes, calculation of the error-locator polynomial, calculation of the error-location numbers, and calculation of the error magnitudes.

Let  $\beta = \alpha^{\frac{1}{3}}$  be a primitive element of the cyclic group  $G_s$ , where  $s = p^{3mt} - 1$ . Let  $\mathbf{c} = (c_1, c_2, \dots, c_n)$  be a transmitted codeword and  $\mathbf{b} = (b_1, b_2, \dots, b_n)$  be the received vector. Thus the error vector is given by  $\mathbf{e} = (e_1, e_2, \dots, e_n) = \mathbf{b} - \mathbf{c}$ . Let  $\eta = (\alpha_1, \alpha_2, \dots, \alpha_n) = (\beta^{k_1}, \beta^{k_2}, \dots, \beta^{k_n})$  be a vector over  $G_s$ . Suppose that  $\nu \leq t$  is the number of errors which occurred at locations  $x_1 =$

$\alpha_{i_1}, x_2 = \alpha_{i_2}, \dots, x_\nu = \alpha_{i_\nu}$  with values  $y_1 = e_{i_1}, y_2 = e_{i_2}, \dots, y_\nu = e_{i_\nu}$ . The syndrome values  $s_l$  of an error vector  $\mathbf{e} = (e_1, e_2, \dots, e_n)$  is defined as

$$s_l = \sum_{j=1}^n e_j h(\alpha_j)^{-1} \alpha_j^l, \quad \text{for } l \geq 0.$$

Since  $\mathbf{s} = (s_0, s_1, \dots, s_{3r-1}) = \mathbf{b}H^t = \mathbf{e}H^t$ , it follows that the first  $3r$  syndrome values  $s_l$  can be calculated from the received vector  $\mathbf{b}$  as follow

$$s_l = \sum_{j=1}^n e_j h(\alpha_j)^{-1} \alpha_j^l = \sum_{j=1}^n b_j h(\alpha_j)^{-1} \alpha_j^l, \quad \text{for } l = 0, 1, 2, \dots, 3r - 1.$$

The elementary symmetric functions  $\sigma_1, \sigma_2, \dots, \sigma_\nu$  of the error-location numbers  $x_1, \dots, x_\nu$  are defined as the coefficients of the polynomial

$$\sigma(X) = \prod_{i=1}^{\nu} (X - x_i) = \sum_{i=0}^{\nu} \sigma_i X^{\nu-i},$$

where  $\sigma_0 = 1$ . Thus, the decoding algorithm being proposed consists of four major steps: calculation of the syndrome vector  $\mathbf{s}$  from the received vector; calculation of the elementary symmetric functions  $\sigma_1, \sigma_2, \dots, \sigma_\nu$  from  $\mathbf{s}$ , using the modified Berlekamp-Massey algorithm [5]; calculation of the error-location numbers  $x_1, x_2, \dots, x_\nu$  from  $\sigma_1, \sigma_2, \dots, \sigma_\nu$ , that are roots of  $\sigma(X)$ ; and calculation of the error magnitudes  $y_1, y_2, \dots, y_\nu$  from  $x_i$  and  $\mathbf{s}$ , using Forney's procedure [6].

Since the calculation of the vector syndrome is straightforward, it follows that there is no need to comment on Step 1. In Step 2, the calculation of the elementary symmetric functions is equivalent to finding a solution  $\sigma_1, \sigma_2, \dots, \sigma_\nu$ , with minimum possible  $\nu$ , to the following set of linear recurrent equations over  $\mathbb{R}$ , i.e.,

$$s_{j+\nu} + s_{j+\nu-1}\sigma_1 + \dots + s_{j+1}\sigma_{\nu-1} + s_j\sigma_\nu = 0, \quad \text{for } j = 0, 1, 2, \dots, (3r-1) - \nu, \quad (3.1)$$

where  $s_0, s_1, \dots, s_{3r-1}$  are the components of the syndrome vector. From the modified Berlekamp-Massey algorithm, it follows that the solutions of Equation (3.1). The algorithm is iterative, in the sense that the following  $n - l_n$  equations

(called *power sums*)

$$\begin{cases} s_n \sigma_0^{(n)} + s_{n-1} \sigma_1^{(n)} + \cdots + s_{n-l_n} \sigma_{l_n}^{(n)} = 0 \\ s_{n-1} \sigma_0^{(n)} + s_{n-2} \sigma_1^{(n)} + \cdots + s_{n-l_n-1} \sigma_{l_n}^{(n)} = 0 \\ \vdots \\ s_{l_n+1} \sigma_0^{(n)} + s_{l_n} \sigma_1^{(n)} + \cdots + s_1 \sigma_{l_n}^{(n)} = 0 \end{cases}$$

are satisfied with  $l_n$  as small as possible and  $\sigma_0^{(0)} = 1$ . The polynomial  $\sigma^{(n)}(X) = \sigma_0^{(n)} + \sigma_1^{(n)}X + \cdots + \sigma_{l_n}^{(n)}X^{l_n}$  represents the solution at the  $n$ -th stage. The  $n$ -th *discrepancy* is denoted by  $d_n$  and defined by  $d_n = s_n \sigma_0^{(n)} + s_{n-1} \sigma_1^{(n)} + \cdots + s_{n-l_n} \sigma_{l_n}^{(n)}$ . The modified Berlekamp-Massey algorithm is formulated as: the inputs to the algorithm are the syndromes  $s_0, s_1, \dots, s_{3r-1}$  which belong to  $\mathfrak{R}$ . The output of the algorithm is a set of values  $\sigma_i$ , for  $i = 1, 2, \dots, \nu$ , such that Equation (3.1) holds with minimum  $\nu$ . Let  $\sigma^{(-1)}(X) = 1$ ,  $l_{-1} = 0$ ,  $d_{-1} = 1$ ,  $\sigma^{(0)}(X) = 1$ ,  $l_0 = 0$  and  $d_0 = s_0$  be the a set of initial conditions to start the algorithm as in Peterson [7]. The steps of the algorithm are:

1.  $n \leftarrow 0$ .
2. If  $d_n = 0$ , then  $\sigma^{(n+1)}(X) \leftarrow \sigma^{(n)}(X)$  and  $l_{n+1} \leftarrow l_n$  and to go 5).
3. If  $d_n \neq 0$ , then find  $m \leq n-1$  such that  $d_n - yd_m = 0$  has a solution  $y$  and  $m - l_m$  has the largest value. Then,  $\sigma^{(n+1)}(X) \leftarrow \sigma^{(n)}(X) - yX^{n-m}\sigma^{(m)}(X)$  and  $l_{n+1} \leftarrow \max\{l_n, l_m + n - m\}$ .
4. If  $l_{n+1} = \max\{l_n, n + 1 - l_n\}$  then go to step 5, else search for a solution  $D^{(n+1)}(X)$  with minimum degree  $l$  in the range  $\max\{l_n, n + 1 - l_n\} \leq l < l_{n+1}$  such that  $\sigma^{(m)}(X)$  defined by  $D^{(n+1)}(X) - \sigma^{(n)}(X) = X^{n-m}\sigma^{(m)}(X)$  is a solution for the first  $m$  power sums,  $d_m = -d_n$ , with  $\sigma_0^{(m)}$  a zero divisor in  $\mathfrak{R}$ . If such a solution is found,  $\sigma^{(n+1)}(X) \leftarrow D^{(n+1)}(X)$  and  $l_{n+1} \leftarrow l$ .
5. If  $n < 3r - 1$ , then  $d_n = s_n + s_{n-1}\sigma_1^{(n)} + \cdots + s_{n-l_n}\sigma_{l_n}^{(n)}$ .
6.  $n \leftarrow n + 1$ ; if  $n < 3r - 1$  go to 2); else stop.

The coefficients  $\sigma_1^{(3r)}, \sigma_2^{(3r)}, \dots, \sigma_\nu^{(3r)}$  satisfy Equation (3.1).

At Step 3, the set of possible error-location numbers is a subset of  $G_s$  and the solution to Equation (3.1) is generally not unique and the reciprocal polynomial  $\rho(Z)$  of the polynomial  $\sigma^{(3r)}(Z)$  (output by the modified Berlekamp-Massey algorithm), may not be the correct error-locator polynomial  $(Z - x_1)(Z - x_2) \cdots (Z - x_\nu)$ , where  $x_j = \beta^{k_j}$ , for  $j = 1, 2, \dots, \nu$  and  $i = 1, 2, \dots, n$ , are the correct error-location numbers. Now, compute the roots  $z_1, z_2, \dots, z_\nu$  of  $\rho(Z)$ , and among the  $x_i = \beta^{k_j}$ , for  $j = 1, 2, \dots, n$ , select those  $x_i$ 's such that  $x_i - z_i$  are zero divisors in  $\mathfrak{R}$ . The selected  $x_i$ 's will be the correct error-location numbers and each  $k_j$ , for  $j = 1, 2, \dots, n$ , indicates the position  $j$  of the error in the codeword.

At Step 4, the calculation of the error magnitude is based on Forney's procedure [6]. The error magnitude is given by

$$y_j = \frac{\sum_{l=0}^{\nu-1} \sigma_{jl} s_{\nu-1-l}}{E_j \sum_{l=0}^{\nu-1} \sigma_{jl} x_j^{\nu-1-l}}, \quad (3.2)$$

for  $j = 1, 2, \dots, \nu$ , where the coefficients  $\sigma_{jl}$  are recursively defined by  $\sigma_{j,i} = \sigma_i + x_j \sigma_{j,i-1}$ , for  $i = 0, 1, \dots, \nu - 1$ , starting with  $\sigma_0 = \sigma_{j,0} = 1$ . The  $E_j = h(x_i)^{-1}$ , for  $i = 1, 2, \dots, \nu$ , are the corresponding location of errors in the vector  $\mathbf{w}$ . It follows from [4] that the denominator in Equation (3.2) is always a unit in  $\mathfrak{R}$ .

**Example 1.** Let  $B = GF(2)[i]$  and  $\mathfrak{R} = \frac{B[X; \frac{1}{3}Z_0]}{(f(X^{\frac{1}{3}}))}$ , where  $f(X^{\frac{1}{3}}) = (X^{\frac{1}{3}})^9 + (X^{\frac{1}{3}})^3 + 1$  is irreducible over  $B$ . If  $X^{\frac{1}{3}} = Y$ , then  $f(Y) = Y^9 + Y^3 + 1$ . If  $\beta = \alpha^{\frac{1}{3}}$  is a root of  $f(Y)$ , then  $\alpha^{\frac{1}{3}}$  generates a cyclic group  $G_s$  of order  $s = 2^{3(3)} - 1$ . If  $h(X^{\frac{1}{3}}) = (X^{\frac{1}{3}})^4 + (X^{\frac{1}{3}})^3 + 1$ ,  $T = \{\alpha, \alpha^5, \alpha^2, 1, \alpha^3, \alpha^{\frac{7}{2}}, \alpha^4, \alpha^6\}$  and  $\omega = \{\alpha^2, \alpha^4, \alpha^4, 1, \alpha, \alpha^{\frac{1}{2}}, \alpha^3, \alpha^2\}$ , then

$$H = \begin{bmatrix} \alpha^2 & \alpha^4 & \alpha^4 & 1 & \alpha & \alpha^{\frac{1}{2}} & \alpha^3 & \alpha^2 \\ \alpha^3 & \alpha^2 & \alpha^2 & 1 & \alpha^4 & \alpha^4 & 1 & \alpha \\ \alpha^4 & 1 & \alpha^5 & 1 & 1 & \alpha^{\frac{1}{2}} & \alpha^4 & 1 \\ \alpha^5 & \alpha^5 & 1 & 1 & \alpha^3 & \alpha^4 & \alpha & \alpha^6 \end{bmatrix}$$

is the parity check matrix of a Goppa code over  $B$  of length 8 and, by Theorem 1, the minimum Hamming distance is at least 5. Now, if the received vector is given by  $b = (0, i, 0, 0, 0, 0, 0, 0)$ , then the syndrome vector is given by  $s = bH^t = (i\alpha^3, i\alpha, i\alpha^6, i\alpha^4)$ . Applying the modified Berlekamp-Massey algorithm, it follows that  $\sigma^{(4)}(Z) = 1 + \alpha^5 Z$ . The root of  $\rho(Z) = Z + \alpha^5$  (the reciprocal of  $\sigma^{(4)}(Z)$ ) is  $z_1 = \alpha^5$ . Among the elements of  $G_s$  it follows that  $x_1 = \alpha^5$

is such that  $x_1 - z_1 = 0$  is a zero divisor in  $\mathfrak{R}$ . Therefore,  $x_1$  is the correct error-location number, and  $k_2 = 5$  indicates that one error has occurred in the second coordinate of the codeword. Finally, applying Forney's method to  $s$  and  $x_1$ , gives  $y_1 = i$ . Therefore, the error pattern is given by  $e = (0, i, 0, 0, 0, 0, 0, 0)$ .

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