

DIMENSION OF BIVARIATE SPLINE SPACE OF
DEGREE SIX ON UNIFORM TYPE-2 TRIANGULATION

Sun-Kang Chen^{1 §}, Lei-Shi², Cheng-Qing Li³

Department of Mathematics
Honghe University
Mengzi, Yunnan, 661100, P.R. CHINA
e-mail: sunkang_chen@yahoo.com.cn

Abstract: In this paper, by using the technique of the well-known Bernstein-Bézier representation, and enforcing some additional smoothness conditions, the dimension of bivariate spline space of degree six on uniform type-2 triangulation is determined. Compared with [1], this method reduces the dimension by $5mn$.

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Key Words: bivariate splines, uniform type-2 triangulation, Bernstein-Bézier, dimension

1. Introduction

Let $\Omega = [0, x_m] \otimes [0, y_n]$ be a rectangle. For $0 = x_0 < x_1 < \cdots < x_m$ and $0 = y_0 < y_1 < \cdots < y_n$, Ω is divided into mn small rectangle $\Omega_{ij} = [x_i, x_{i+1}] \otimes [y_j, y_{j+1}]$, $i = 0, 1, \cdots, m-1$, $j = 0, 1, \cdots, n-1$, by mesh lines,

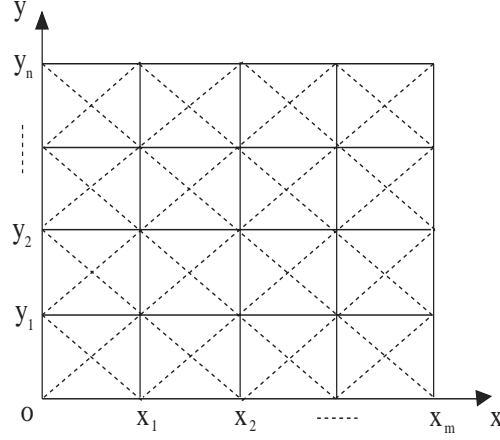
$$x = x_i, i = 0, 1, \cdots, m-1, \text{ and } y = y_j, j = 0, 1, \cdots, n-1.$$

Let $h_i = x_i - x_{i-1}$, $t_j = y_j - y_{j-1}$ for $i = 1, 2, \cdots, m$, and $j = 1, 2, \cdots, n$, If $h_i \equiv h$, $i = 1, 2, \cdots, m$, and $t_j \equiv t$, $j = 1, 2, \cdots, n$, and the triangulation generated

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[§]Correspondence author

Figure 1: A uniform type-2 triangulation $\Delta_{mn}^{(2)}$

by drawing all northeast and northwest diagonals in all small rectangles, then the triangulation is called uniform type-2 triangulation, and it is denoted by $\Delta_{mn}^{(2)}$ (Figure 1).

In this paper, we are interested in the spline function space of smoothness order 2 and degree 6:

$$S_6^2(\Delta_{mn}^{(2)}) = \left\{ s \in C^2(\Omega) : s|_T \in \mathcal{P}_6, \text{ for all triangles } T \text{ in } \Delta_{mn}^{(2)} \right\}, \quad (1)$$

where \mathcal{P}_6 denotes the space of bivariate polynomials of total degree being at most 6.

The dimension of $S_6^2(\Delta_{mn}^{(2)})$ can be determined by Chui and Wang's results [1]. In 1997, Lai and Schumaker [2] studied the C^2 superspline space of degree 6 on triangulated quadrangulation, this is a generalization of the results of [1]. In this paper, by enforcing some additional smoothness conditions, a minimal determining set of subspace of $S_6^2(\Delta_{mn}^{(2)})$ is constructed. It implies that the dimension of the space is reduced, compared to [1].

2. Preliminaries

Throughout the paper, we use the well-known Bernstein-Bézier technique of bivariate splines [3]. Let $T := \langle v_1, v_2, v_3 \rangle$ be a triangle in Δ , where v_1, v_2 and v_3 are three vertices of T . Then every polynomial $s \in \mathcal{P}_d$ associated with

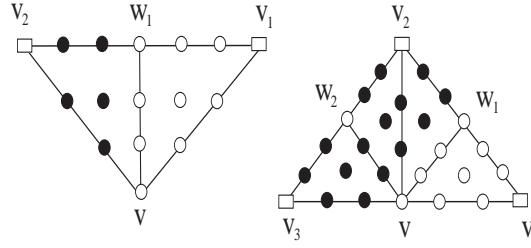


Figure 2: A minimal determining set for $S_3^2(star(v))(n = 2, n = 3)$ in Lemma 2.1.

T can be written as

$$s := \sum_{i+j+k=d} c_{ijk}^T \mathcal{B}_{ijk}^d, \quad (2)$$

where $\{\mathcal{B}_{ijk}^d\}_{i+j+k=d}$ is the Bernstein basis polynomials of degree d on the triangle T . The coefficients $\{c_{ijk}^T\}_{i+j+k=d}$ are called B-coefficients of s associated with domain points $\mathcal{D}_T := \{\xi_{ijk}^T := (iv_0 + jv_1 + kv_2)/d\}_{i+j+k=d}$. Let $\mathcal{D}_{d,\Delta}$ be the union of the sets of domain points associated with the triangles of Δ .

Let $S_d^0(\Delta)$ be the space of continuous splines of degree d on the triangulation Δ . A subset $\mathcal{M} \subseteq \mathcal{D}_{d,\Delta}$ is said to be a determining set for a spline space $S \subseteq S_d^0(\Delta)$ if $s \in S$ and $c_\xi = 0$ for all $\xi \in \mathcal{M}$, then $c_\eta = 0$ for all $\eta \in \mathcal{D}_{d,\Delta}$, i.e., $s \equiv 0$. Moreover, \mathcal{M} is called a minimal determining set for S if there is no smaller determining set. It is known that $\dim S = |\mathcal{M}|$, where $|\mathcal{M}|$ denotes the cardinality of \mathcal{M} .

Let $T := \langle v_0, v_1, v_2 \rangle$ and $\tilde{T} := \langle v_3, v_2, v_1 \rangle$ be two adjacent triangles, they share the common edge $e := \langle v_1, v_2 \rangle$. Let $s|_T$ and $s|_{\tilde{T}}$ to denote the restrictions of s on T and \tilde{T} with B-coefficients c_{ijk} and \tilde{c}_{ijk} , respectively. Following [4], for any $0 \leq n \leq m \leq d$, let $\tau_{e,m}^n$ be the linear functional defined on $S_d^0(\Delta)$ by

$$\tau_{e,m}^n s := \tilde{c}_{n,m-n,d-m} - \sum_{i+j+k=n} c_{i,j+d-m,k+m-n} \mathcal{B}_{ijk}^n(v_3), \quad (3)$$

then the condition that s is C^r smooth across the edge e is equivalent to

$$\tau_{e,m}^n s = 0, \quad n \leq m \leq d, \quad 0 \leq n \leq r. \quad (4)$$

First we give there lemmas established in Lai and Schumaker [2].

Lemma 2.1. Suppose that v is a boundary vertex of $\Delta_{mn}^{(2)}$ with $2n-1$ edges attached, let the boundary vertices of $star(v)$ be $v, v_1, w_1, v_2, w_2, \dots, w_{n-1}, v_n$ in counterclockwise order. Then the following set of $2n+7$ domain points is a MDS for $S_3^2(star(v))$:

- (1) $\xi_{ijk}^{v, v_1, w_1}, i+j+k=3,$
- (2) $\xi_{030}^{v, v_i, w_i}, \xi_{003}^{v, v_i, w_i}, i=2, \dots, n-1,$
- (3) $\xi_{003}^{v, w_{n-1}, v_n}.$

These points are marked with \circ and \square in Fig. 2.

Lemma 2.2. Suppose that v is an interior vertex of $\Delta_{mn}^{(2)}$ with 8 edges attached, let the boundary vertices of $star(v)$ be $v_1, w_1, v_2, w_2, v_3, w_3, v_4, w_4$ in counterclockwise order. Then the following set of 14 domain points is a MDS for $S_3^2(star(v))$:

- (1) $\xi_{ijk}^{v, w_4, v_1}, i+j+k=3,$
- (2) $\xi_{030}^{v, v_i, w_i}, i=2, 3, 4,$
- (3) $\xi_{003}^{v, v_3, w_3}.$

These points are marked with \circ and \square in Fig. 3.

Lemma 2.3. Let $star(v)$ consist 4 triangles surrounding a vertex v formed by two crossing lines. We denote the boundary vertices of $star(v)$ by v_1, v_2, v_3, v_4 . Let $T_l = \langle v, v_l, v_{l+1} \rangle$ for $l=1, 2, 3, 4$, where we identify $v_5 = v_1$. Then the following set of 49 domain points is a MDS for $S_6^2(star(v))$:

- (1) $\xi_{ijk}^{T_l}, i+j+k=6, j \geq 3, l=1, 2, 3, 4,$
- (2) $\xi_{222}^{T_l}, l=1, 2, 3, 4,$
- (3) $\xi_{420}^{T_l}, l=1, 2, 3, 4,$
- (4) $\xi_{600}^{T_1}.$

These points are marked with $\circ, \square, \triangle$ and $*$ in Fig. 4.

Following Lemma 2.3, we can get a lemma by enforcing some additional smoothness conditions across the interior edges of $star(v)$.

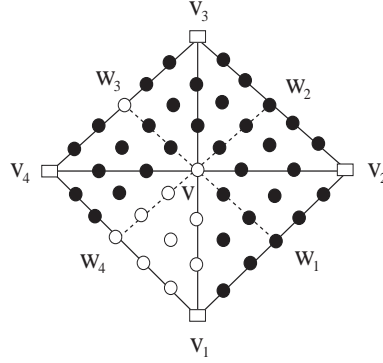
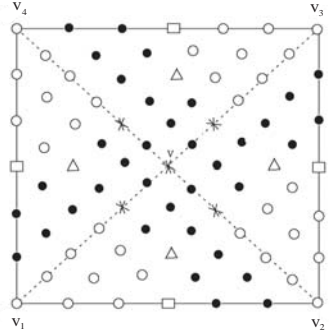
Lemma 2.4. Let $star(v)$ be a triangulation described in Lemma 2.3. Let $\hat{S}_6^2(star(v))$ be the subspace of $S_6^2(star(v))$ satisfying the following set of additional smoothness conditions:

$$\tau_{e_i, 4}^3 s = 0, \quad i = 1, 2, 3, 4 \text{ and } \tau_{e_1, 6}^3 s = 0, \quad (5)$$

then $\dim \hat{S}_6^2(star(v)) = 44$, and the following set of 44 domain points is a MDS for $\hat{S}_6^2(star(v))$:

- (1) $\xi_{ijk}^{T_l}, i+j+k=6, j \geq 3, l=1, 2, 3, 4,$
- (2) $\xi_{222}^{T_l}, l=1, 2, 3, 4,$

These points are marked with \circ, \square and \triangle in Fig. 4.

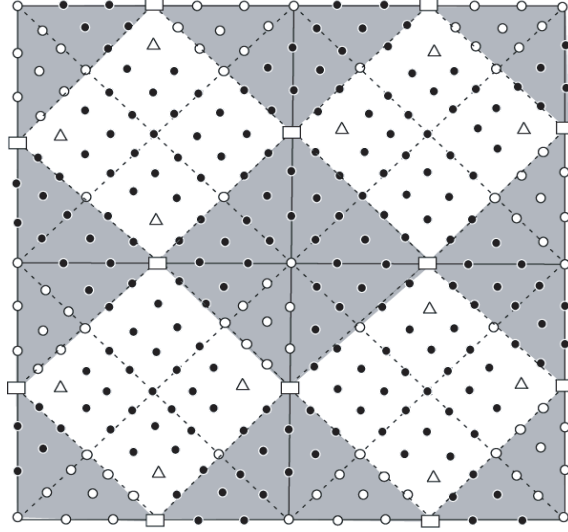

 Figure 3: A minimal determining set for $S_3^2(star(v))$ in Lemma 2.2

 Figure 4: A minimal determining set for $S_3^2(star(v))$ in Lemma 2.3

Proof. We can prove this lemma easily by using Lemma 2.3 and conditions of (5). \square

3. Dimension of $\hat{S}_6^2(\Delta_{mn}^{(2)})$

Theorem 3.1. Let $\Delta_{mn}^{(2)}$ be an uniform type-2 triangulation, let $\hat{S}_6^2(\Delta_{mn}^{(2)})$ be the set of all splines $s \in S_6^2(\Delta_{mn}^{(2)})$ such that s satisfies the additional smoothness conditions in each small rectangle of Ω as described in Lemma 2.4. Then

$$\dim \hat{S}_6^2(\Delta_{mn}^{(2)}) = 14mn + 12(m + n) + 6.$$

Figure 5: A minimal determining set for $\hat{S}_6^2(\Delta_{mn}^{(2)})$

Proof. We choose the following domain points set P to construct a determining set for $\hat{S}_6^2(\Delta_{mn}^{(2)})$:

(1) For each boundary vertices v of rectangle Ω , choose 9 or 10 points in the 3-disks around v as in Lemma 2.1 which are marked with \circ in Fig. 2.

(2) For each interior vertices v of rectangle Ω , choose 10 points in the 3-disks around v as in Lemma 2.2 which are marked with \circ in Fig. 3.

(3) For each edge of Ω , choose 2 points as in Lemma 2.4 which are marked with \square and \triangle in Fig. 4.

To show that P is a determining set, suppose all of the B-coefficients of $s \in \hat{S}_6^2(\Delta_{mn}^{(2)})$ in P to zero. Then by (1) and (2), using Lemma 2.1 and Lemma 2.2, all B-coefficients in the 3-disks around every vertex must be zero. Since the B-coefficients in (3) are zero, using the C^2 conditions across the edges we see that all B-coefficients of ξ_{222} on both sides of any edge of Ω are zero. Finally, Lemma 2.4 imply that s must vanish identically inside each small rectangle. So P is a determining set for $\hat{S}_6^2(\Delta_{mn}^{(2)})$, and $\dim \hat{S}_6^2(\Delta_{mn}^{(2)}) \leq |P|$.

It is easy to see that

$$|P| = 10(m+1)(n+1) - 4 + 2(m+1)n + 2(n+1)m,$$

it is noted that $\dim S_6^2(\Delta_{mn}^{(2)}) = 19mn + 12(m+n) + 6$ [1]. Our space $\hat{S}_6^2(\Delta_{mn}^{(2)})$ is the subspace of $S_6^2(\Delta_{mn}^{(2)})$ that satisfies $5mn$ additional special smoothness

conditions. Thus,

$$19mn + 12(m + n) + 6 - 5mn \leq \dim \hat{S}_6^2(\Delta_{mn}^{(2)}) \leq |P| = 14mn + 12(m + n) + 6,$$

and we conclude that $\dim \hat{S}_6^2(\Delta_{mn}^{(2)}) = 14mn + 12(m + n) + 6$, and P is a MDS for $\hat{S}_6^2(\Delta_{mn}^{(2)})$. \square

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